This listing of claims will replace all prior versions, and listings, of claims in the

application:

Listing of Claims:

Claim 1 (currently amended): A system for diagnosing the possibility of disease in one

of a first body part and a second substantially similar body part by impedance

measurements, the system comprising:

a first body part module for injecting a first current into the first body part and for

receiving a corresponding first voltage signal;

a second body part module for injecting a second current into the second body

part and for receiving a corresponding second voltage signal:

a correction module for obtaining a first correction factor for the first body part

and a second correction factor for the second body part, the first and second correction

factors accounting for impedances inherent in non-body part sources, the correction

module including a magnitude correction module for calculating a magnitude correction

factor, and a phase correction module for calculating a phase correction factor, where

the first correction factor is composed of the magnitude correction factor and the phase

correction factor; and

an impedance module for calculating a first impedance from the first current, the

first voltage signal and the first correction factor, and for calculating a second

impedance from the second current, the second voltage signal and the second

correction factor, wherein the first and second impedances are used to diagnose the

possibility of disease.

Claim 2 (original): The system of claim 1, wherein the non-body part sources that give

rise to inherent impedances include skin covering the body parts and parts of the

system.

Claim 3 (canceled)

Claim 4 (currently amended): The system of claim [[3]] 1, wherein the correction

module includes a magnitude correction table to calculate the magnitude correction

factor, the magnitude correction table containing calibration impedance magnitude

 $(|Z_{cal}|)$  data and associated magnitude correction factor  $(C_{max}(|Z_{cal}|))$  data.

Claim 5 (original): The system of claim 4, further comprising a calibration apparatus to

form the magnitude correction table.

Claim 6 (original): The system of claim 5, wherein the calibration apparatus includes an

electrical model of the first body part, a variable interface resistance and the impedance

module.

Claim 7 (original): The system of claim 6, wherein the impedance module includes a bipolar unit for calculating a bipolar impedance,  $Z_{\text{RP}}$ , from a bipolar voltage measurement made by the first body part module on the first body part, the magnitude of the bipolar impedance used by the correction module to obtain the correction factor.

Claim 8 (original): The system of claim 7, wherein the correction module uses the magnitude correction table and the magnitude of the bipolar impedance to obtain the magnitude correction factor, which is given by  $C_{\text{max}}(|Z_{\text{BP}}|)$ .

Claim 9 (original): The system of claim 8, wherein an uncorrected first impedance, Z<sup>naw</sup>. is calculated by the impedance module from the first current and the first voltage signal.

Claim 10 (original): The system of claim 9, wherein the magnitude of the first impedance, Z, is calculated by the impedance module according to

$$|Z| = C_{\text{mag}}(|Z_{\text{BP}}|) \times |Z^{\text{raw}}|$$

Claim 11 (currently amended): The system of claim [[3]] 1, wherein the correction module includes a phase correction table to calculate the phase correction factor, the phase correction table containing calibration impedance magnitude ( $|Z_{ca}|$ ) data and associated phase correction factor  $(C_{rb}(|Z_{cal}|))$  data.

Appl. No. 10/722,511

Amdt. dated April 11, 2007

Reply to Office action of October 11, 2006

Claim 12 (original): The system of claim 11, further comprising a calibration apparatus

to form the phase correction table.

Claim 13 (original): The system of claim 12, wherein the calibration apparatus includes

an electrical model of the first body part, a variable interface resistance and the

impedance module.

Claim 14 (original): The system of claim 13, wherein the impedance module includes a

bipolar unit for calculating a bipolar impedance,  $Z_{RP}$ , from a bipolar voltage

measurement made by the first body part module on the first body part, the magnitude

of the bipolar impedance used by the correction module to obtain the correction factor.

Claim 15 (original): The system of claim 14, wherein the correction module uses the

information from the phase correction table and the magnitude of the bipolar impedance

to obtain the phase correction factor  $C_{nb}(|Z_{RP}|)$ .

Claim 16 (original): The system of claim 15, wherein an uncorrected first impedance,

 $Z^{\text{unc}}$ , is calculated by the impedance module from the first current and the first voltage

signal.

Claim 17 (original): The system of claim 16, wherein the phase of the first

impedance, Z, is calculated by the impedance module according to

Appl. No. 10/722,511 Amdt. dated April 11, 2007 Reply to Office action of October 11, 2006

$$arg(Z) = C_{arg}(Z_{RP}) \times arg(Z^{unc})$$
.

Claim 18 (currently amended): A method for diagnosing the possibility of disease in one of a first body part and a second substantially similar body part by impedance measurements, the method comprising:

injecting a first current into the first body part;
receiving a corresponding first voltage signal;
injecting a second current into the second body part;
receiving a corresponding second voltage signal:

obtaining a first correction factor for the first body part and a second correction factor for the second body part, the first and second correction factors accounting for impedances inherent in non-body part sources, the step of obtaining including calculating a magnitude correction factor, and calculating a phase correction factor, where the first correction factor is composed of the magnitude correction factor and the phase correction factor;

calculating a first impedance from the first current, the first voltage signal and the first correction factor with an impedance module; and

calculating a second impedance from the second current, the second voltage signal and the second correction factor with the impedance module, wherein the first and second impedances are used to diagnose the possibility of disease. Claim 19 (original): The method of claim 18, wherein the non-body part sources that

give rise to inherent impedances include skin covering the body parts and parts of the

svstem.

Claim 20 (canceled)

Claim 21 (currently amended): The method of claim [[20]] 19, wherein the step of

calculating a magnitude correction factor includes using a magnitude correction table,

the magnitude correction table containing calibration impedance magnitude ( $|Z_{cal}|$ ) data

and associated magnitude correction factor  $(C_{\text{max}}(|Z_{\text{cal}}|))$  data.

Claim 22 (original): The method of claim 21, further comprising forming the magnitude

correction table with a calibration apparatus that includes an electrical model of the first

body part, a variable interface resistance and the impedance module.

Claim 23 (currently amended): The method of claim 22, further comprising:

performing a bipolar voltage measurement on the first body part; and

calculating a bipolar impedance,  $Z_{\mathrm{BP}}$ , from the bipolar voltage, the magnitude of

the bipolar impedance used to obtain the correction factor.

Claim 24 (original): The method of claim 23, wherein the magnitude correction table and the magnitude of the bipolar impedance are used to obtain the magnitude correction factor, which is given by  $C_{max}(|Z_{RP}|)$ .

Claim 25 (original): The method of claim 24, further comprising calculating an uncorrected first impedance, Zraw, from the first current and the first voltage signal.

Claim 26 (original): The method of claim 25, wherein the magnitude of the first impedance, Z, is given by

$$|Z| = C_{\text{mag}}(|Z_{\text{BP}}|) \times |Z^{\text{raw}}|$$
.

Claim 27 (original): The method of claim 20, wherein the step of calculating a phase correction factor includes using a phase correction table to calculate the phase correction factor, the phase correction table containing calibration impedance magnitude ( $|Z_{cal}|$ ) data and associated phase correction factor ( $C_{ch}(|Z_{cal}|)$ ) data.

Claim 28 (original): The method of claim 27, further comprising forming the phase correction table with a calibration apparatus that includes an electrical model of the first body part, a variable interface resistance and the impedance module.

Claim 29 (currently amended): The method of claim 28, further comprising: performing a bipolar voltage measurement on the first body part; and calculating a bipolar impedance,  $Z_{\rm BP}$ , from the bipolar voltage, the magnitude of the bipolar impedance used to obtain the correction factor.

Claim 30 (original): The method of claim 29, wherein the phase correction table and the magnitude of the bipolar impedance are used to obtain the phase correction factor, which is given by  $C_{\rm pk}(|Z_{\rm BP}|)$ .

Claim 31 (original): The method of claim 30, further comprising calculating an uncorrected first impedance,  $Z^{mw}$ , from the first current and the first voltage signal.

Claim 32 (original): The method of claim 31, wherein the phase of the first impedance,  $\mathbb{Z}$ , is given by

$$arg(Z) = C_{arg}(Z_{BP}) \times arg(Z^{unc})$$
.